































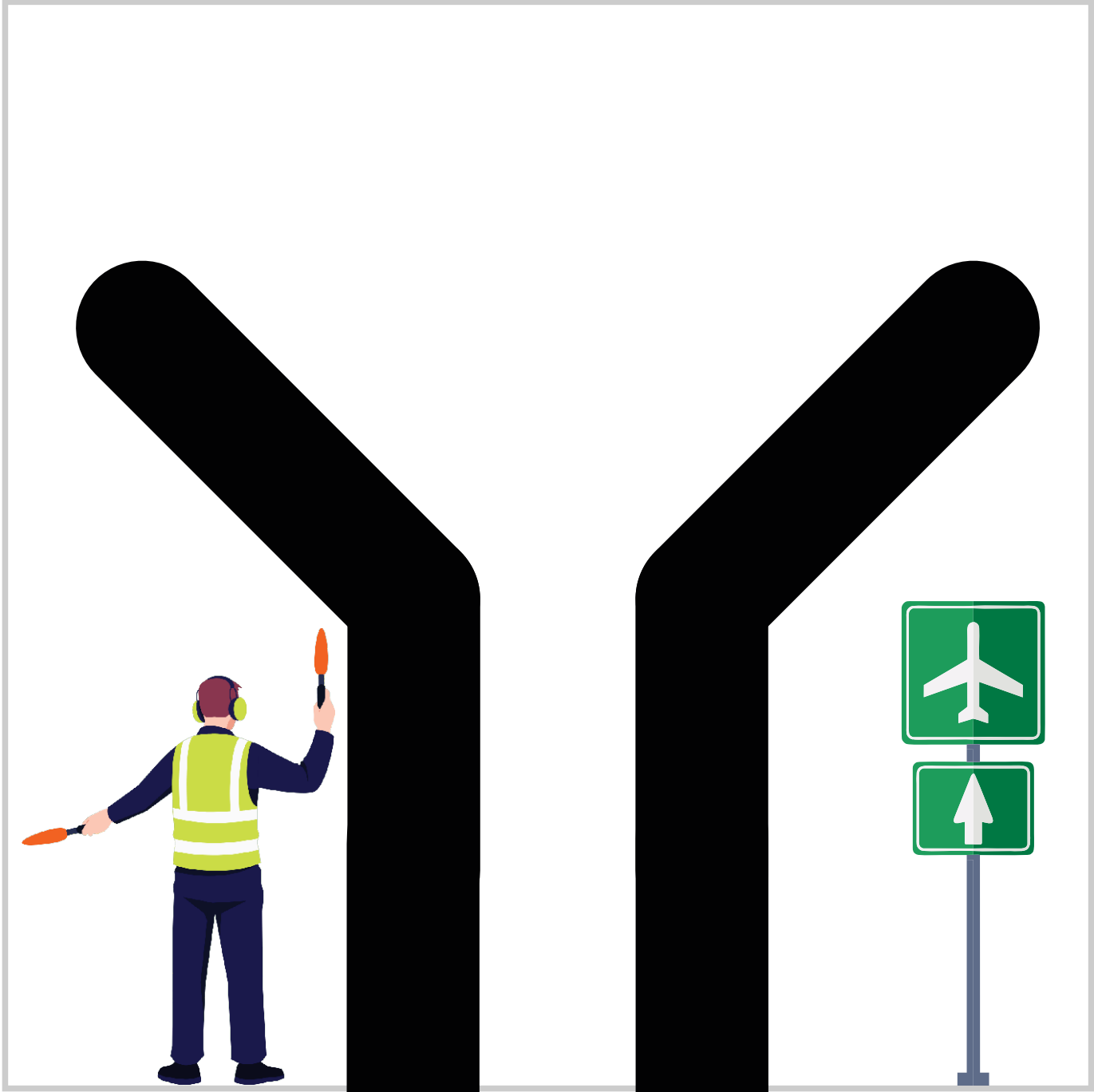


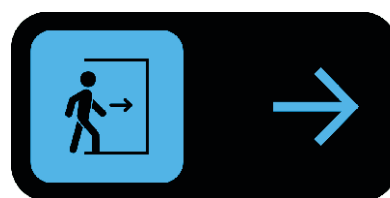


## TERMINAL B

TIME	DESTINATION	FLIGHT	BOARDING	GATE
14:45	                               			



# CILJ

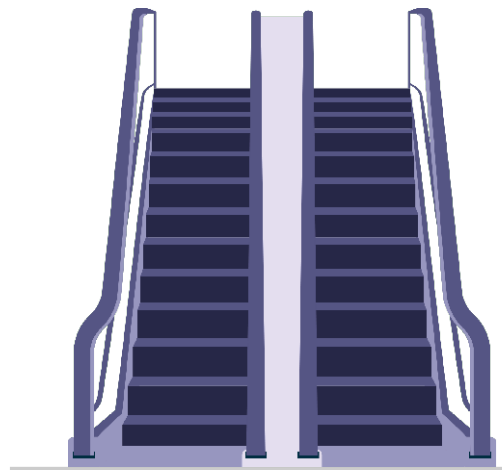






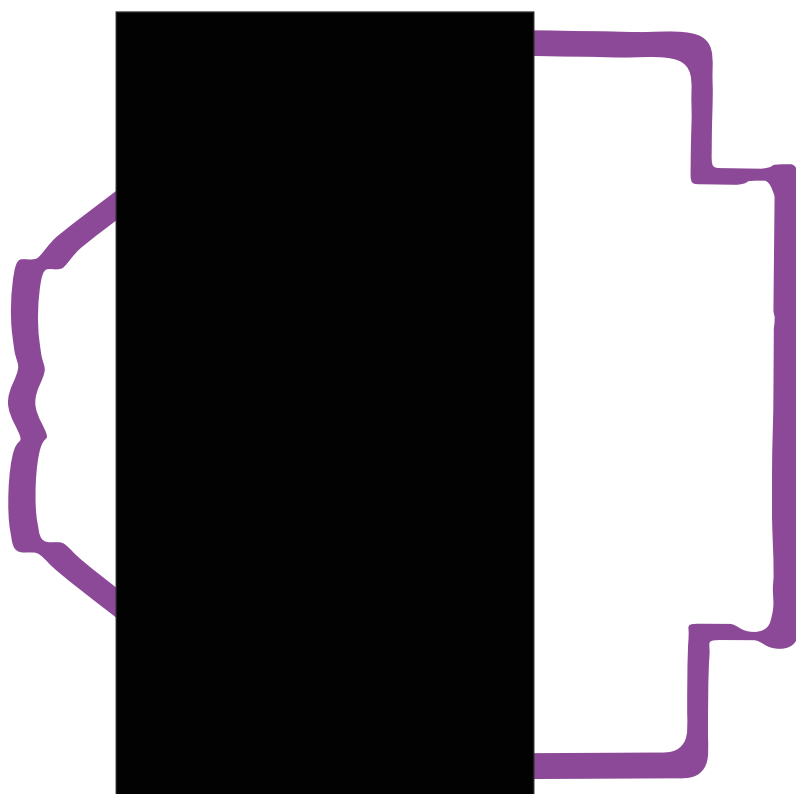


**Terminals**



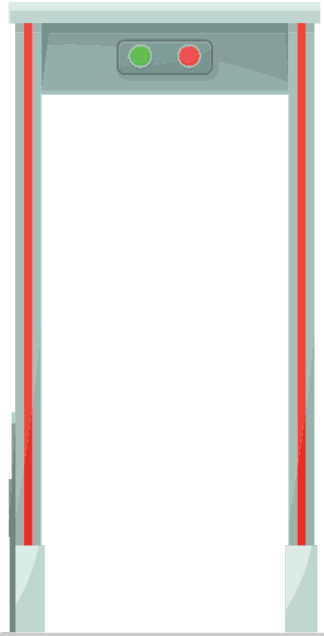
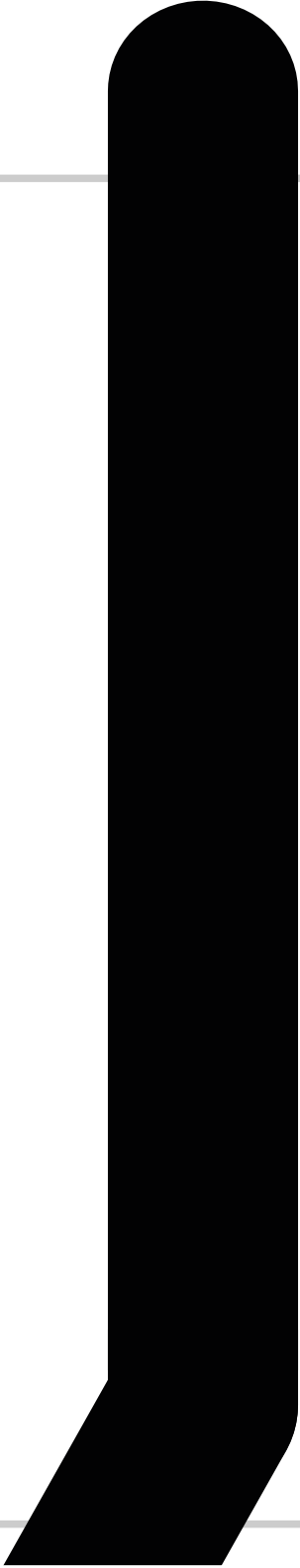


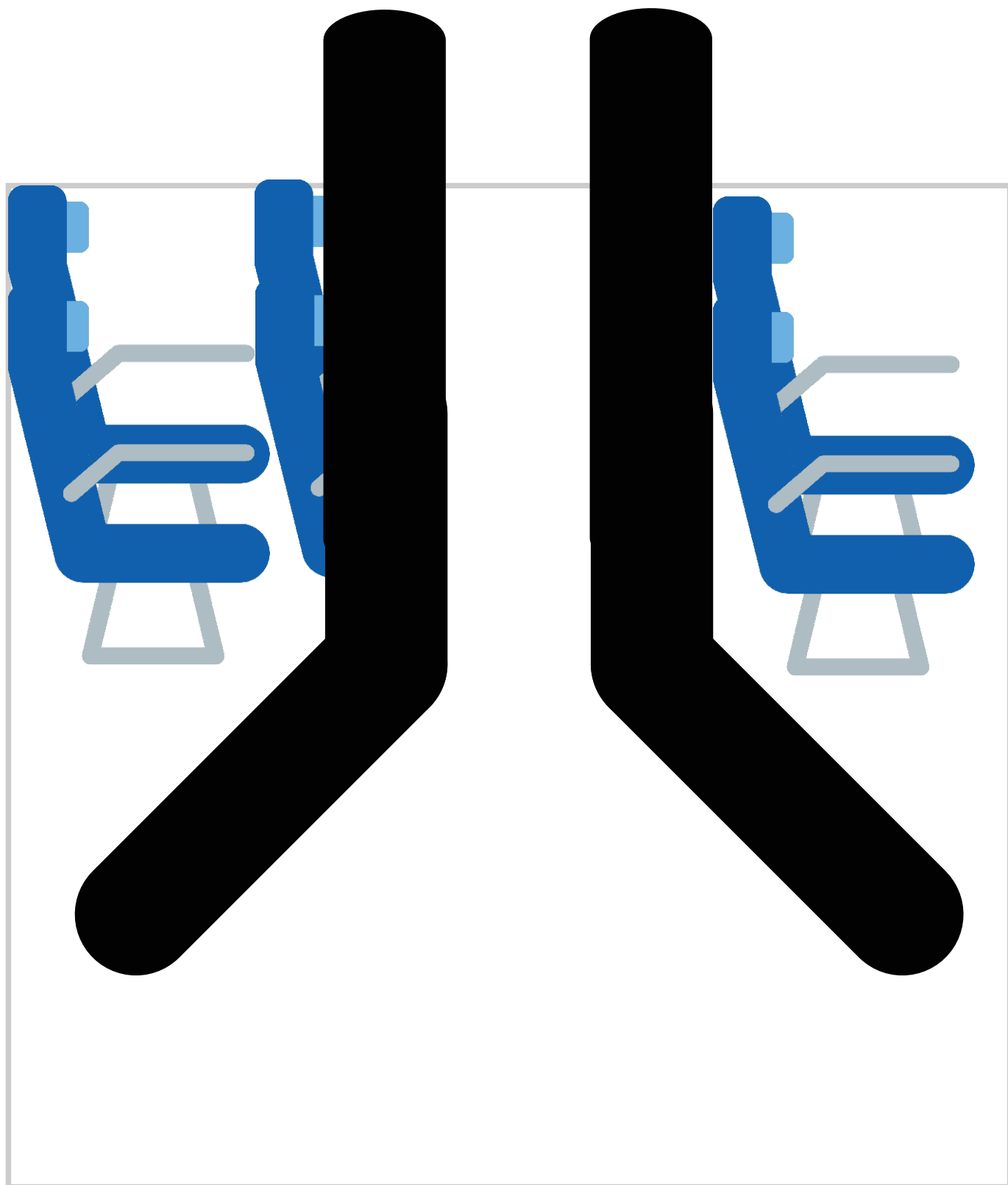
# Zona za kalibraciju



1. Postavite robot tako da je sa svih 5 senzora na crnoj površini.
2. Držite pritisnutu tipku za kalibraciju koja se nalazi s prednje lijeve strane robota oko 1 sekunde.
3. Kada dvije gornje svjetleće diode zatrepere nekoliko puta, kalibracija je gotova.

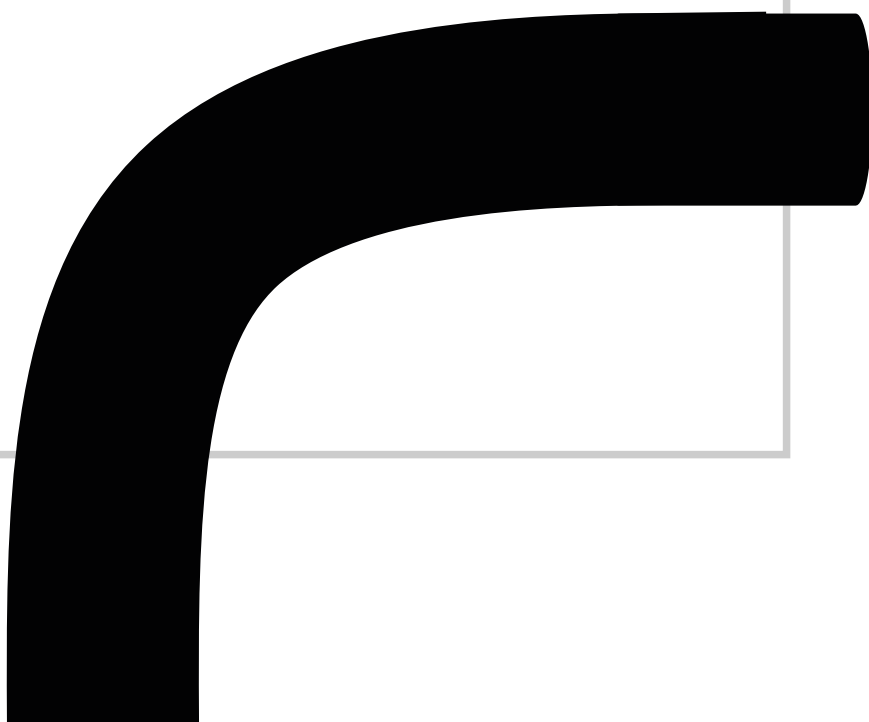




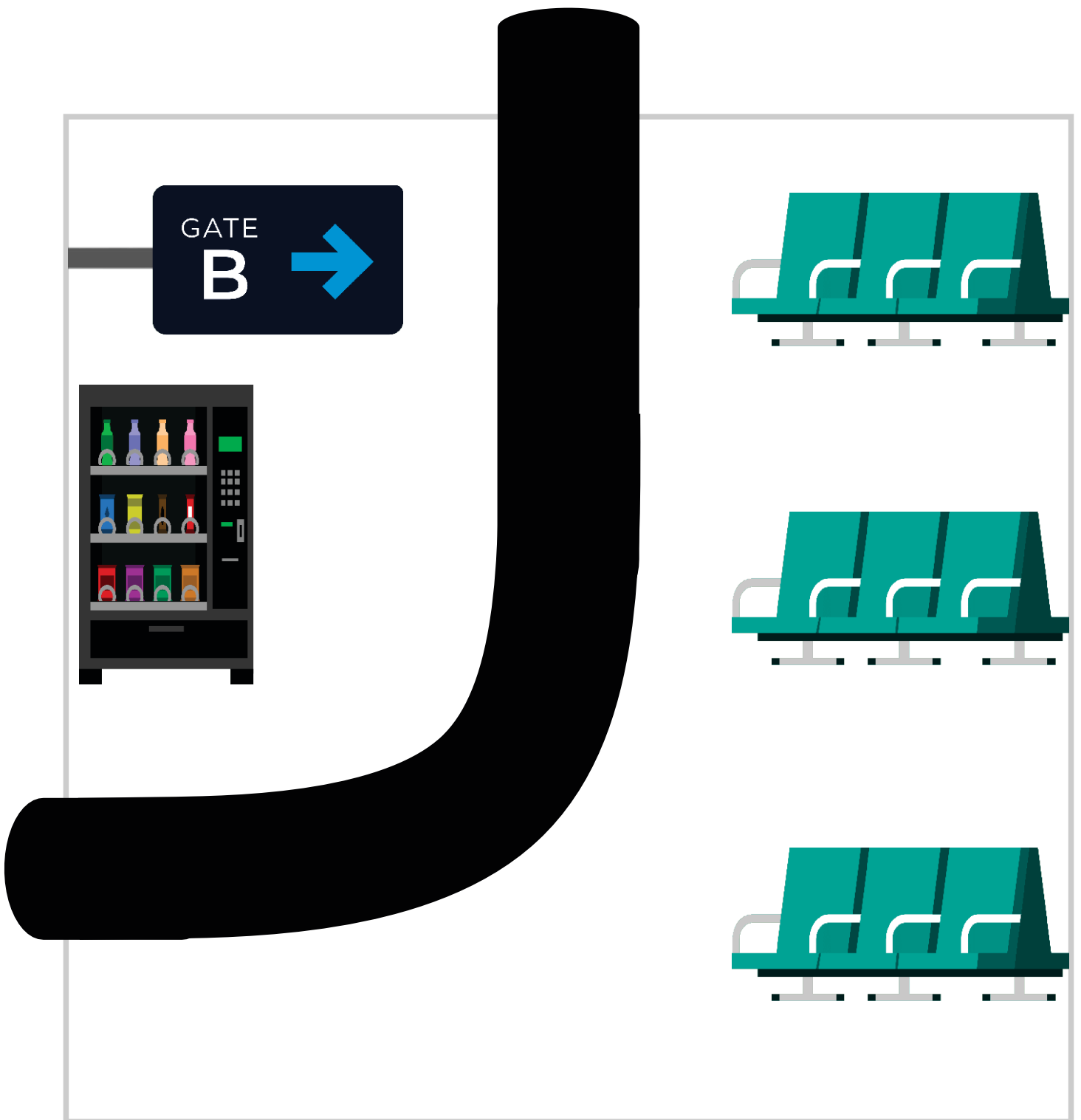




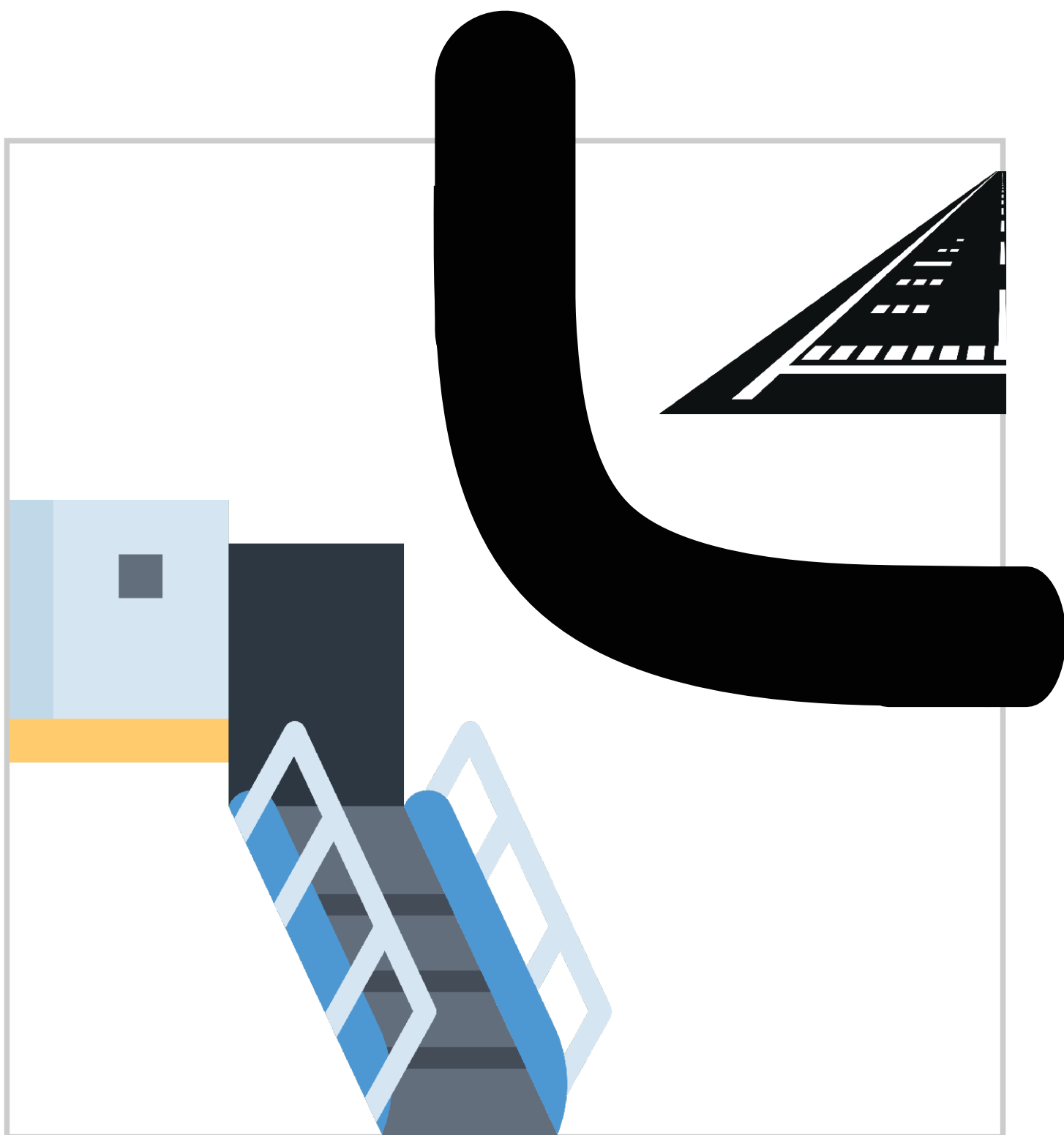
**CROATIAN  
MAKERS**

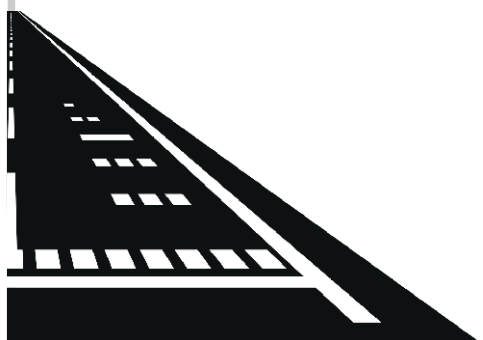
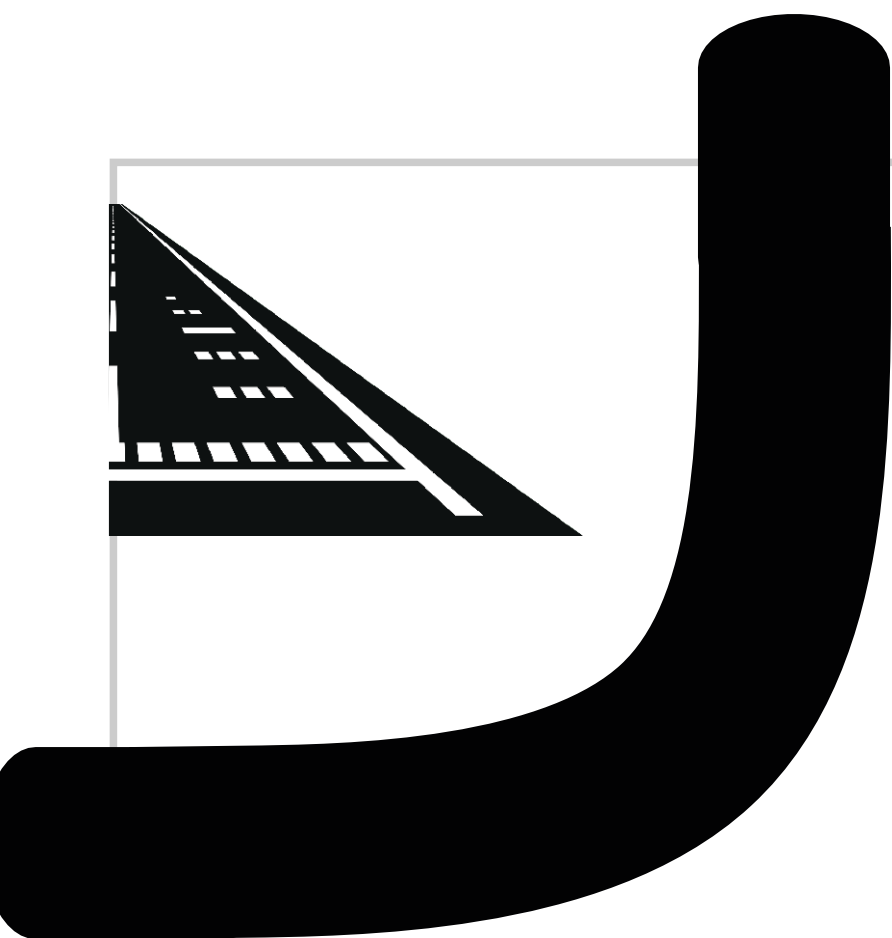












# START





